A non-equilibrium multi-component model with miscible conditions

Jean Bussac

LMJL, Nantes Université

45ème Congrès National d'Analyse Numérique - 14 juin 2022


## IV Nantes U Université

## Motivations

- Multiphase flow modelling
- Industrial applications : nuclear safety (loss of coolant scenario in pressurized water reactors, vapor explosion...)


Figure: LOCA scenario (IRSN)

## A brief and non-exhaustive historical review

- 1986, Baer and Nunziato: model for a two-phase compressible mixture
- 1992, Embid and Baer: analysis of this latter model
- 2002, Coquel, Gallouet, Hérard and Seguin: $\left(P_{I}, V_{I}\right)$ entropy-consistent closure, and jump conditions for a class of two-phase flow models
- 2007, Hérard: three-phase flow model
- 2014, Coquel, Hérard, Saleh and Seguin: deeper analysis of the two-phase model (convexity of the entropy, symmetrization)
- 2016, Müller, Hantke and Richter: generalization for a mixture of $N$ immiscible phases
- 2019, Hérard and Mathis: two-phase flow model with a miscible condition (three fields)
- 2021, Hérard, Hurisse and Quibel: three-phase flow model with a miscible condition (four fields)


## A brief and non-exhaustive historical review

- 1986, Baer and Nunziato: model for a two-phase compressible mixture
- 1992, Embid and Baer: analysis of this latter model
- 2002, Coquel, Gallouet, Hérard and Seguin: $\left(P_{I}, V_{I}\right)$ entropy-consistent closure, and jump conditions for a class of two-phase flow models
- 2007, Hérard: three-phase flow model
- 2014, Coquel, Hérard, Saleh and Seguin: deeper analysis of the two-phase model (convexity of the entropy, symmetrization)
- 2016, Müller, Hantke and Richter: generalization for a mixture of $N$ immiscible phases
- 2019, Hérard and Mathis: two-phase flow model with a miscible condition (three fields)
- 2021, Hérard, Hurisse and Quibel: three-phase flow model with a miscible condition (four fields)


## Objective

Generalizing these latter works that include the miscible hypothesis to any number of phases.

## Plan

(1) Generalized model
(2) Definition of the interfacial pressures
(3) Analysis of the convective part
(4) Admissible source terms

## Plan

(1) Generalized model
(2) Definition of the interfacial pressures
(3) Analysis of the convective part
(4) Admissible source terms

## The mixture

- Mixture of $N$ phases and $M$ fields
- "phase" means a state of the matter and "field" a component in a given phase
- All the miscible components are contained in the Nth phase
- $K=M-N+1$ miscible components


Figure: $N$ phases and $M$ fields mixture

## Mixture description

- We note $\mathcal{K}$ the set of fields, and each field $k$ is depicted by its state vector $\mathbf{Y}_{k}=\left(\alpha_{k}, \rho_{k}, v_{k}, e_{k}\right)$, where
- $\alpha_{k}$ is the volume fraction
- $\rho_{k}$ is the phasic density
- $v_{k}$ is the phasic speed
- $e_{k}$ is the phasic internal energy


## Mixture description

- We note $\mathcal{K}$ the set of fields, and each field $k$ is depicted by its state vector $\mathbf{Y}_{k}=\left(\alpha_{k}, \rho_{k}, v_{k}, e_{k}\right)$, where
- $\alpha_{k}$ is the volume fraction
- $\rho_{k}$ is the phasic density
- $v_{k}$ is the phasic speed
- $e_{k}$ is the phasic internal energy
- Volumic constraints

$$
\left\{\begin{array}{l}
\sum_{k=1}^{N} \alpha_{k}=1 \\
\alpha_{k}=\alpha_{N} \text { for } k \geq N
\end{array}\right.
$$

## Mixture description

- We note $\mathcal{K}$ the set of fields, and each field $k$ is depicted by its state vector $\mathbf{Y}_{k}=\left(\alpha_{k}, \rho_{k}, v_{k}, e_{k}\right)$, where
- $\alpha_{k}$ is the volume fraction
- $\rho_{k}$ is the phasic density
- $v_{k}$ is the phasic speed
- $e_{k}$ is the phasic internal energy
- Volumic constraints

$$
\left\{\begin{array}{l}
\sum_{k=1}^{N} \alpha_{k}=1 \\
\alpha_{k}=\alpha_{N} \text { for } k \geq N
\end{array}\right.
$$

- By introducing $m_{k}=\alpha_{k} \rho_{k}$, we define the mixture entropy

$$
\sigma(\mathbf{Y})=\sum_{k \in \mathcal{K}} m_{k} \sigma_{k}\left(\mathbf{Y}_{k}\right)
$$

where $\sigma_{k}$ is the specific entropy of the phase $k$.

## System of equations

For $k=1, \ldots, N$

$$
\partial_{t} \alpha_{k}+V_{I}(\mathbf{Y}) \partial_{x} \alpha_{k}=\Phi_{k}(\mathbf{Y})
$$

## System of equations

For $k=1, \ldots, N$

$$
\partial_{t} \alpha_{k}+V_{I}(\mathbf{Y}) \partial_{x} \alpha_{k}=\Phi_{k}(\mathbf{Y})
$$

For $k \in \mathcal{K}$

$$
\begin{gathered}
\partial_{t}\left(m_{k}\right)+\partial_{x}\left(m_{k} v_{k}\right)=\Gamma_{k}(\mathbf{Y}) \\
\partial_{t}\left(m_{k} v_{k}\right)+\partial_{x}\left(m_{k} v_{k}^{2}+\alpha_{k} p_{k}\right)+\sum_{l=1, \neq k}^{M} P_{k, l}(\mathbf{Y}) \partial_{x} \alpha_{l}=S_{q, k}(\mathbf{Y}) \\
\partial_{t}\left(m_{k} E_{k}\right)+\partial_{x}\left(m_{k} v_{k}\left(E_{k}+\frac{p_{k}}{\rho_{k}}\right)\right)+\sum_{l=1, \neq k}^{M} P_{k, l}(\mathbf{Y}) V_{I}(\mathbf{Y}) \partial_{x} \alpha_{l}=S_{E, k}(\mathbf{Y}),
\end{gathered}
$$

System of equations

For $k=1, \ldots, N$

$$
\partial_{t} \alpha_{k}+V_{I}(\mathbf{Y}) \partial_{x} \alpha_{k}=\Phi_{k}(\mathbf{Y})
$$

For $k \in \mathcal{K}$

$$
\begin{gathered}
\partial_{t}\left(m_{k}\right)+\partial_{x}\left(m_{k} v_{k}\right)=\Gamma_{k}(\mathbf{Y}) \\
\partial_{t}\left(m_{k} v_{k}\right)+\partial_{x}\left(m_{k} v_{k}^{2}+\alpha_{k} p_{k}\right)+\sum_{l=1, \neq k}^{M} P_{k, l}(\mathbf{Y}) \partial_{x} \alpha_{l}=S_{q, k}(\mathbf{Y}) \\
\partial_{t}\left(m_{k} E_{k}\right)+\partial_{x}\left(m_{k} v_{k}\left(E_{k}+\frac{p_{k}}{\rho_{k}}\right)\right)+\sum_{l=1, \neq k}^{M} P_{k, l}(\mathbf{Y}) V_{I}(\mathbf{Y}) \partial_{x} \alpha_{l}=S_{E, k}(\mathbf{Y}),
\end{gathered}
$$

$\rightsquigarrow$ Closure laws: nonconservative interfacial terms $P_{k, l}(\mathbf{Y})$ and $V_{I}(\mathbf{Y})+$ source terms

## Several constraints

Since the system is isolated, the source terms must verify

$$
\sum_{k \in \mathcal{K}} \Gamma_{k}(\mathbf{Y})=0, \quad \sum_{k \in \mathcal{K}} S_{q, k}(\mathbf{Y})=0, \quad \sum_{k \in \mathcal{K}} S_{E, k}(\mathbf{Y})=0 .
$$

Moreover, as we consider no vacuum occurrence

$$
\sum_{k=1}^{N} \Phi_{k}(\mathbf{Y})=0
$$

## Several constraints

Since the system is isolated, the source terms must verify

$$
\sum_{k \in \mathcal{K}} \Gamma_{k}(\mathbf{Y})=0, \quad \sum_{k \in \mathcal{K}} S_{q, k}(\mathbf{Y})=0, \quad \sum_{k \in \mathcal{K}} S_{E, k}(\mathbf{Y})=0
$$

Moreover, as we consider no vacuum occurrence

$$
\sum_{k=1}^{N} \Phi_{k}(\mathbf{Y})=0
$$

Besides, the interfacial quantities $P_{k, l}$ should cancel each other

$$
\sum_{k \in \mathcal{K}} \sum_{\substack{l \in \mathcal{K} \\ l \neq k}} P_{k, l}(\mathbf{Y}) \partial_{x} \alpha_{l}=0
$$

to preserve the mixture conservative equations on momentum and energy.

## Entropy equation

The mixture entropy verifies the following equation

$$
\partial_{t} \sigma(\mathbf{Y})+\partial_{x} f_{\sigma}(\mathbf{Y})=\mathcal{A}_{\sigma}\left(\mathbf{Y}, \partial_{x} \mathbf{Y}\right)+R H S_{\sigma}(\mathbf{Y})
$$

where

- $f_{\sigma}(\mathbf{Y})=\sum_{k \in \mathcal{K}} m_{k} \sigma_{k} v_{k}$ is the entropy flux
- $\mathcal{A}_{\sigma}\left(\mathbf{Y}, \partial_{x} \mathbf{Y}\right)$ contains the interfacial contribution
- $R H S_{\sigma}(\mathbf{Y})$ corresponds to the source terms


## Entropy equation

The mixture entropy verifies the following equation

$$
\partial_{t} \sigma(\mathbf{Y})+\partial_{x} f_{\sigma}(\mathbf{Y})=\mathcal{A}_{\sigma}\left(\mathbf{Y}, \partial_{x} \mathbf{Y}\right)+R H S_{\sigma}(\mathbf{Y})
$$

where

- $f_{\sigma}(\mathbf{Y})=\sum_{k \in \mathcal{K}} m_{k} \sigma_{k} v_{k}$ is the entropy flux
- $\mathcal{A}_{\sigma}\left(\mathbf{Y}, \partial_{x} \mathbf{Y}\right)$ contains the interfacial contribution
- $R H S_{\sigma}(\mathbf{Y})$ corresponds to the source terms
$\rightsquigarrow$ These production terms have to be non-negative to satisfy the second law of thermodynamics


## Plan

## (1) Generalized model

(2) Definition of the interfacial pressures

## (3) Analysis of the convective part

4 Admissible source terms

## Approach

The proof relies on the previous ones in different situations: immiscible two, three and then $N$-phase flow [Coq+02; Hér07; MHR16], or more recently for hybrid mixtures in [HM19; HHQ21].

## Goal

Determine interfacial pressure and velocity terms that correspond to the minimal entropy dissipation model: $\mathcal{A}_{\sigma}\left(\mathbf{Y}, \partial_{x} \mathbf{Y}\right)=0$.

## Approach

The proof relies on the previous ones in different situations: immiscible two, three and then $N$-phase flow [Coq+02; Hér07; MHR16], or more recently for hybrid mixtures in [HM19; HHQ21].

## Goal

Determine interfacial pressure and velocity terms that correspond to the minimal entropy dissipation model: $\mathcal{A}_{\sigma}\left(\mathbf{Y}, \partial_{x} \mathbf{Y}\right)=0$.
$\rightsquigarrow$ Define new interfacial terms $\left(K_{k, l}\right)$ from $\left(P_{k, l}\right)$, defined for $k=1, \ldots, M$, $l=1, \ldots, N-1$ to rewrite the PDE system that only use the $N-1$ first $\partial_{x} \alpha_{k}$

## Approach

The proof relies on the previous ones in different situations: immiscible two, three and then $N$-phase flow [Coq+02; Hér07; MHR16], or more recently for hybrid mixtures in [HM19; HHQ21].

## Goal

Determine interfacial pressure and velocity terms that correspond to the minimal entropy dissipation model: $\mathcal{A}_{\sigma}\left(\mathbf{Y}, \partial_{x} \mathbf{Y}\right)=0$.
$\rightsquigarrow$ Define new interfacial terms $\left(K_{k, l}\right)$ from $\left(P_{k, l}\right)$, defined for $k=1, \ldots, M$, $l=1, \ldots, N-1$ to rewrite the PDE system that only use the $N-1$ first $\partial_{x} \alpha_{k}$
$\rightsquigarrow$ Explicit the condition $\mathcal{A}_{\sigma}\left(\mathbf{Y}, \partial_{x} \mathbf{Y}\right)=0$ by using the independence of the $N-1$ first $\partial_{x} \alpha_{l}$, that give $N-1$ equations for each $l=1, \ldots, N-1$

$$
\mathcal{A}_{\sigma}\left(\mathbf{Y}, \partial_{x} \mathbf{Y}\right)=0 \Longleftrightarrow \forall l \leq N-1, \sum_{k=1}^{M} \frac{1}{T_{k}}\left(v_{k}-V_{I}\right)\left(K_{k, l}+\chi_{k, l} p_{k}\right)=0
$$

## Approach

$\rightsquigarrow$ Assume the convex combination (galilean invariance) $V_{I}(\mathbf{Y})=\sum_{k \in \mathcal{K}} \beta_{i} v_{i}$ that give the relations

$$
v_{k}-V_{I}=\sum_{i=1}^{k-1} \sum_{j=1}^{i}\left(-\beta_{j}\right)\left(v_{i}-v_{i+1}\right)+\sum_{i=k}^{M-1} \sum_{j=i+1}^{M}\left(\beta_{j}\right)\left(v_{i}-v_{i+1}\right)
$$

## Approach

$\rightsquigarrow$ Assume the convex combination (galilean invariance) $V_{I}(\mathbf{Y})=\sum_{k \in \mathcal{K}} \beta_{i} v_{i}$ that give the relations

$$
v_{k}-V_{I}=\sum_{i=1}^{k-1} \sum_{j=1}^{i}\left(-\beta_{j}\right)\left(v_{i}-v_{i+1}\right)+\sum_{i=k}^{M-1} \sum_{j=i+1}^{M}\left(\beta_{j}\right)\left(v_{i}-v_{i+1}\right)
$$

$\rightsquigarrow$ Each of these equations can be split into $M-1$ new equations for each $i=1, \ldots, M-1$ by using the independence of the $M-1$ velocities differences $v_{i+1}-v_{i}$

$$
\ldots \Longleftrightarrow \forall l \leq N-1, i \leq M-1, \quad \sum_{k=1}^{i} c^{i} \frac{1}{T_{k}} K_{k, l}-\sum_{k=i+1}^{M} c_{i} \frac{1}{T_{k}} K_{k, l}=d_{l}^{i}
$$

## Approach

$\rightsquigarrow$ Assume the convex combination (galilean invariance) $V_{I}(\mathbf{Y})=\sum_{k \in \mathcal{K}} \beta_{i} v_{i}$ that give the relations

$$
v_{k}-V_{I}=\sum_{i=1}^{k-1} \sum_{j=1}^{i}\left(-\beta_{j}\right)\left(v_{i}-v_{i+1}\right)+\sum_{i=k}^{M-1} \sum_{j=i+1}^{M}\left(\beta_{j}\right)\left(v_{i}-v_{i+1}\right)
$$

$\rightsquigarrow$ Each of these equations can be split into $M-1$ new equations for each $i=1, \ldots, M-1$ by using the independence of the $M-1$ velocities differences $v_{i+1}-v_{i}$

$$
\ldots \Longleftrightarrow \forall l \leq N-1, i \leq M-1, \quad \sum_{k=1}^{i} c^{i} \frac{1}{T_{k}} K_{k, l}-\sum_{k=i+1}^{M} c_{i} \frac{1}{T_{k}} K_{k, l}=d_{l}^{i}
$$

$\rightsquigarrow$ By adding the balance momentum equation, we obtain, for each $l=1, \ldots, N-1$, a linear systems of size $M \times M$ and of unknowns $\boldsymbol{K}_{l}=\left(K_{1, l}, \ldots, K_{M, l}\right)$

$$
\forall l \leq N-1, \quad \boldsymbol{A} \boldsymbol{K}_{l}=\boldsymbol{d}_{l}
$$

## Linear systems

$$
\forall l \leq N-1, \quad \boldsymbol{A} \boldsymbol{K}_{l}=\boldsymbol{d}_{l}
$$

## Linear systems

$$
\forall l \leq N-1, \quad \boldsymbol{A} \boldsymbol{K}_{l}=\boldsymbol{d}_{l}
$$

where

$$
\boldsymbol{A}=\left(\begin{array}{ccccc}
c^{1} a_{1} & -c_{1} a_{2} & -c_{1} a_{3} & \ldots & -c_{1} a_{M} \\
c^{2} a_{1} & c^{2} a_{2} & -c_{2} a_{3} & \ldots & -c_{2} a_{M} \\
\ldots & & & & \ldots \\
c^{M-1} a_{1} & c^{M-1} a_{2} & \ldots & c^{M-1} a_{M-1} & -c_{M-1} a_{M} \\
1 & 1 & \ldots & \cdots & 1
\end{array}\right) \in \mathcal{M}_{M}(\mathbb{R})
$$

## Linear systems

$$
\forall l \leq N-1, \quad \boldsymbol{A} \boldsymbol{K}_{l}=\boldsymbol{d}_{l}
$$

where

\[

\]

## Linear systems

$$
\forall l \leq N-1, \quad \boldsymbol{A} \boldsymbol{K}_{l}=\boldsymbol{d}_{l}
$$

where

$$
\begin{aligned}
& \boldsymbol{A}=\left(\begin{array}{ccccc}
c^{1} a_{1} & -c_{1} a_{2} & -c_{1} a_{3} & \ldots & -c_{1} a_{M} \\
c^{2} a_{1} & c^{2} a_{2} & -c_{2} a_{3} & \ldots & -c_{2} a_{M} \\
\ldots & & & \ldots & \ldots \\
c^{M-1} a_{1} & c^{M-1} a_{2} & \ldots & c^{M-1} a_{M-1} & -c_{M-1} a_{M} \\
1 & 1 & \ldots & \ldots & 1
\end{array}\right) \in \mathcal{M}_{M}(\mathbb{R}) \\
& \boldsymbol{K}_{l}=\left(K_{1, l}, K_{2, l}, \ldots, K_{M, l}\right)^{\top} \\
& \boldsymbol{d}_{l}=\left(d_{l}^{1}, d_{l}^{2}, \ldots, d_{l}^{M}\right)^{\top}
\end{aligned}
$$

where $a_{k}=T_{k}^{-1}$, and $\left(\boldsymbol{d}_{l}\right)_{l=1, \ldots, N-1}$ depends on the phasic pressures $p_{k}$, the phasic temperatures $T_{k}$, and the convex combination of coefficients $\beta_{k}$

## Regularity of A

## Proposition

We have the following expression

$$
\operatorname{det} \boldsymbol{A}=\overline{a_{1}} c_{1}+\overline{a_{M}} c^{M-1}+\sum_{i=2}^{M-1} \overline{a_{i}} \beta_{i} .
$$

Moreover, if the phasic temperatures are all positive, then for any convex combination of $V_{I}$, $\operatorname{det} \boldsymbol{A}>0$ and so $\boldsymbol{A}$ is regular.

## Regularity of A

## Proposition

We have the following expression

$$
\operatorname{det} \boldsymbol{A}=\overline{a_{1}} c_{1}+\overline{a_{M}} c^{M-1}+\sum_{i=2}^{M-1} \overline{a_{i}} \beta_{i} .
$$

Moreover, if the phasic temperatures are all positive, then for any convex combination of $V_{I}$, $\operatorname{det} \boldsymbol{A}>0$ and so $\boldsymbol{A}$ is regular.

## Thereom (Existence and uniqueness of the interfacial pressures)

Under the same hypotheses, the interfacial pressures ( $K_{k, l}$ ) are uniquely defined.

## Regularity of A

## Proposition

We have the following expression

$$
\operatorname{det} \boldsymbol{A}=\overline{a_{1}} c_{1}+\overline{a_{M}} c^{M-1}+\sum_{i=2}^{M-1} \overline{a_{i}} \beta_{i} .
$$

Moreover, if the phasic temperatures are all positive, then for any convex combination of $V_{I}$, $\operatorname{det} \boldsymbol{A}>0$ and so $\boldsymbol{A}$ is regular.

## Thereom (Existence and uniqueness of the interfacial pressures)

Under the same hypotheses, the interfacial pressures ( $K_{k, l}$ ) are uniquely defined.
$\rightsquigarrow$ Remark: the lack of an explicit form of the $\left(K_{k, l}\right)$ has several consequences. For instance, we cannot verify that a flow initially at rest and at temperature and pressure equilibria will remain steady, (RIP condition, [HJ21])

## Plan

## (1) Generalized model

(2) Definition of the interfacial pressures
(3) Analysis of the convective part

## (4) Admissible source terms

## Analysis of the convective part

## Proposition (Hyperbolicity)

The considered system is hyperbolic under the classical non-resonance condition $c_{k}^{2} \neq\left(v_{k}-V_{I}\right)^{2}$.
$\checkmark$ The proof is close to the immiscible case [MHR16]
$\rightsquigarrow$ Nature of the coupling wave $V_{I}$ and its Riemann invariants must be determined

## Analysis of the convective part

## Proposition (Hyperbolicity)

The considered system is hyperbolic under the classical non-resonance condition $c_{k}^{2} \neq\left(v_{k}-V_{I}\right)^{2}$.
$\checkmark$ The proof is close to the immiscible case [MHR16]
$\rightsquigarrow$ Nature of the coupling wave $V_{I}$ and its Riemann invariants must be determined

## Proposition (Symmetrization)

Under the same non-resonance condition, the system is symmetrizable.
$\checkmark$ The proof is exactly the same than in the immiscible case [MHR16]
$\leadsto$ For a non-resonant initial data, there exists a local-in-time smooth solution to the Cauchy problem (Kato's theorem)

## Plan

## (1) Generalized model

(2) Definition of the interfacial pressures
(3) Analysis of the convective part
(4) Admissible source terms

## Admissible source terms

$\rightsquigarrow$ Source terms are reorganized according to their nature contribution: mechanical, mass transfer, drag effects and thermal

## Admissible source terms

$\rightsquigarrow$ Source terms are reorganized according to their nature contribution: mechanical, mass transfer, drag effects and thermal
$\rightsquigarrow$ Constraints are stated to ensure the non-negativity of $R H S_{\sigma}$ (i.e. the growth of the entropy)

## Admissible source terms

$\rightsquigarrow$ Source terms are reorganized according to their nature contribution: mechanical, mass transfer, drag effects and thermal
$\rightsquigarrow$ Constraints are stated to ensure the non-negativity of $R H S_{\sigma}$ (i.e. the growth of the entropy)
$\checkmark$ Classical conditions obtained on mass transfer, drag effects and thermal contributions
$x$ Less explicit condition on the mechanical contribution $\Phi$ due to the lack of interfacial terms expressions

## Conclusion

- Successful generalization
$\checkmark$ Uniquely defined interfacial pressures
$\checkmark$ Hyperbolicity
$\checkmark$ Symmetrization


## Conclusion

- Successful generalization
$\checkmark$ Uniquely defined interfacial pressures
$\checkmark$ Hyperbolicity
$\checkmark$ Symmetrization
$\rightsquigarrow$ For given $M$ and $N$, the expressions of $\left(K_{k, l}\right)$ can be precised and so the following features
$\rightsquigarrow$ Preservation of an initial state at rest, with a temperature and pressure equilibria (RIP condition)
$\rightsquigarrow$ Classical mechanical constraints


## Conclusion

- Successful generalization
$\checkmark$ Uniquely defined interfacial pressures
$\checkmark$ Hyperbolicity
$\checkmark$ Symmetrization
$\rightsquigarrow$ For given $M$ and $N$, the expressions of $\left(K_{k, l}\right)$ can be precised and so the following features
$\rightsquigarrow$ Preservation of an initial state at rest, with a temperature and pressure equilibria (RIP condition)
$\rightsquigarrow$ Classical mechanical constraints
$\rightsquigarrow$ Preprint online


## Conclusion

- Successful generalization
$\checkmark$ Uniquely defined interfacial pressures
$\checkmark$ Hyperbolicity
$\checkmark$ Symmetrization
$\rightsquigarrow$ For given $M$ and $N$, the expressions of ( $K_{k, l}$ ) can be precised and so the following features
$\rightsquigarrow$ Preservation of an initial state at rest, with a temperature and pressure equilibria (RIP condition)
$\rightsquigarrow$ Classical mechanical constraints
$\rightsquigarrow$ Preprint online

Forecast
$\rightsquigarrow$ Numerical study of the case $M=3$ and $N=2$

## Conclusion

- Successful generalization
$\checkmark$ Uniquely defined interfacial pressures
$\checkmark$ Hyperbolicity
$\checkmark$ Symmetrization
$\rightsquigarrow$ For given $M$ and $N$, the expressions of ( $K_{k, l}$ ) can be precised and so the following features
$\rightsquigarrow$ Preservation of an initial state at rest, with a temperature and pressure equilibria (RIP condition)
$\rightsquigarrow$ Classical mechanical constraints
$\rightsquigarrow$ Preprint online

Forecast
$\rightsquigarrow$ Numerical study of the case $M=3$ and $N=2$

> Thank you for your attention!

