# SDEs with distributional drift and path-by-path solutions

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joint work with Alexandre Richard  $^1$  and Etienne  $\mathsf{Tanr}\acute{e}^2$ 

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3 Path-by-path vs. adapted solutions

## Motivation and definitions

2) Existence of a solution via nonlinear Young integration

Path-by-path vs. adapted solutions

# Regularization by noise

- Let  $B^H$  be a fractional Brownian motion with Hurst parameter  $H \leq 1/2$  ( $\implies W := B^{1/2}$  denotes Brownian motion).
- Well known: Reflected Brownian motion solves the following SDE:

$$X_t = L_t^X(0) + B_t^{1/2}$$
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$$X_t = \int_0^t \phi(X_r) dr + B_t^H, \qquad (\bullet)$$

where  $\phi$  has a singularity, is a finite measure, or is even in a more general class of distributions? (see also Nualart and Ouknine (2002), if H = 1/2 see e.g. Krylov and Röckner (2005), Davie (2007))

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We can rephrase (•) by X̃ = X − B<sup>H</sup>, as

$$\tilde{X}_t = \int_0^t \phi(\tilde{X}_r + B_r^H) dr.$$

• Hope:  $x \mapsto T_t^{B^H} \phi(x) \coloneqq \int_0^t \phi(x + B_r^H) dr$  is regular.

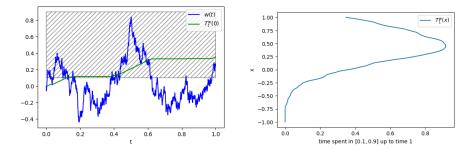
# Averaging operator

## Definition

Let  $w \in \mathcal{C}([0, T], \mathbb{R})$ . For bounded measurable  $\phi : \mathbb{R} \to \mathbb{R}$  let

$$T_t^w \phi(x) \coloneqq \int_0^t \phi(x+w_r) dr \text{ for } (t,x) \in [0,T] \times \mathbb{R}.$$

$$T_t^w \mathbb{1}_{[0.1,0.9]}(x) \coloneqq \int_0^t \mathbb{1}_{[0.1,0.9]}(x+w_r) dr \text{ for } (t,x) \in [0,T] \times \mathbb{R}$$



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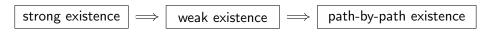
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- We call X : Ω → C([0, T], ℝ) a path-by-path solution if it fulfills (2) for ω ∈ Ω̃ ⊂ Ω with ℙ(Ω̃) = 1.

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## Definition of local time at $x \in \mathbb{R}$

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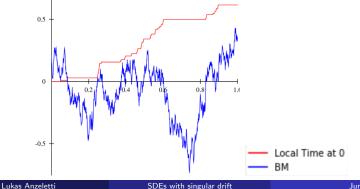
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- $\int_0^t \mathbb{1}_A(W_r) dr = \int_A L_t^W(x) dx \ (\Longrightarrow \ \int_0^t f(W_r) dr = \int_{\mathbb{R}} f(x) L_t^W(x) dx$ for bounded measurable f).

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Let  $H \in (0,1)$ . We call the centered Gaussian process  $\{B_t^H\}_{t \ge 0}$  with covariance function

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- $B^H$  is almost surely  $\gamma$ -Hölder continuous for  $\gamma \in (0, H)$  on any compact interval.

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## Theorem (Catellier and Gubinelli 2016)

Let  $\phi \in C^{\alpha}$  for  $\alpha > 1 - \frac{1}{2H}$ . Then there exists a set of full measure w.r.t. the law of fBm such that there exists a unique solution  $X \in C([0, T])$  to

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In case of  $\phi = \delta_0$  this gives a unique solution for H < 1/4. Main objective: Establish sharpness of this inequality or extend to larger values of H!

## Motivation and definitions



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# Averaging operator defined via the local time

## Equation of interest

$$X_t = \int_0^t \phi(X_r) dr + B_t^H \iff \tilde{X}_t = \int_0^t \phi(\tilde{X}_r + B_r^H) dr, \text{ for } \tilde{X} = X - B^H.$$

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Let  $\phi \in \mathcal{C}_b(\mathbb{R})$  and  $T_t^{B^H}\phi(x) \coloneqq \int_0^t \phi(x+B_r^H)dr$ . Then

$$\int_{0}^{t} \phi(\tilde{X}_{r} + B_{r}^{H}) dr = \lim_{N \to \infty} \sum_{i=1}^{N} \int_{t_{i}}^{t_{i+1}} \phi(\tilde{X}_{t_{i}} + B_{r}^{H}) dr$$
$$= \lim_{N \to \infty} \sum_{i=1}^{N} T_{t_{i}, t_{i+1}}^{B^{H}} \phi(\tilde{X}_{t_{i}}) = \int_{0}^{t} T_{dr}^{B^{H}} \phi(\tilde{X}_{r}).$$

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$$\begin{split} \int_{0}^{t} \phi(\tilde{X}_{r} + B_{r}^{H}) dr &= \lim_{N \to \infty} \sum_{i=1}^{N} \int_{t_{i}}^{t_{i+1}} \phi(\tilde{X}_{t_{i}} + B_{r}^{H}) dr \\ &= \lim_{N \to \infty} \sum_{i=1}^{N} T_{t_{i}, t_{i+1}}^{B^{H}} \phi(\tilde{X}_{t_{i}}) = \int_{0}^{t} T_{dr}^{B^{H}} \phi(\tilde{X}_{r}). \end{split}$$

Let *L* denote the local time of  $B^H$  and  $\phi \in \mathcal{C}_b(\mathbb{R})$ . Notice that

$$T_{s,t}^{B^{H}}\phi(x) = \int_{\mathbb{R}}\phi(x+z)L_{s,t}(z)dz = (\phi \star \check{L}_{s,t})(x), \ \forall x \in \mathbb{R},$$

where 
$$\check{L}_t(x) = L_t(-x)$$

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#### Definition

Let  $\phi$  be a distribution such that  $T^{B^H}\phi$  is **sufficiently regular**. We call  $X: \Omega \times [0, T] \to \mathbb{R}$  a path-by-path solution to  $(\bullet)$  if, for  $\tilde{X} = X - B^H$ ,

$$\tilde{X}_t = \int_0^t T_{dr}^{B^H} \phi(\tilde{X}_r)$$

holds for almost every realisation of  $B^H$ .

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- Search for  $\hat{X}$  in the space of functions with finite 1-variation (via an Euler scheme **next slide**)  $\implies \bigcirc$ .

## Key steps for existence of path-by-path solution

$$\tilde{X}_t = \int_0^t T_{dr}^{B^H} \phi(\tilde{X}_r)$$

- Determine regularity of *T<sup>BH</sup>φ* via the regularity of the local time of a fBm (≈ *L* ∈ *C*<sup>1/2(1-H)</sup>(*C*<sup>1/(2H)-1/2</sup>)). (also see Harang and Perkowski (2021))
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#### Please give me a function with regular local time

Note that the above approach requires no probability theory, having a function with sufficiently regular local time is sufficient.

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#### Theorem

Let  $\eta \in (0,1]$  and  $p \ge 1$  with  $1/p + \eta > 1$ . Let  $A \in C_{[0,T]}^{p\text{-var}}(\mathcal{C}^{\eta})$  with  $A_{s,t}(y) \ge 0$  for all  $y \in \mathbb{R}$  and all  $(s,t) \in \Delta_{[0,T]}$ . Then there exists a solution  $x \in C_{[0,T]}^{1\text{-var}}$  to the nonlinear Young equation

$$x_t = \int_0^t A_{dr}(x_r), \quad \forall t \in [0, T].$$

$$\tag{4}$$

### Sketch of the proof

W.l.o.g., let T = 1. For  $n \in \mathbb{N}$  and  $0 \le k \le n$ , let  $t_k^n := k/n$ ,  $\bar{x}_0^n := 0$  and define recursively

$$\bar{x}_{k+1}^n = \bar{x}_k^n + A_{t_k^n, t_{k+1}^n}(\bar{x}_k^n).$$

We embed  $(\bar{x}^n_k)^n_{k=0}$  into  $\mathcal{C}_{[0,1]}$  by

$$x_t^n = \sum_{0 \le k \le \lfloor nt \rfloor} A_{t_k^n, t \land t_{k+1}^n}(\bar{x}_k^n)$$
(5)

$$= \int_{0}^{t} A_{dr}(x_{r}^{n}) + \sum_{0 \le k \le \lfloor nt \rfloor} \left( \int_{t_{k}^{n}}^{t \land t_{k+1}^{n}} A_{dr}(x_{t_{k}^{n}}^{n}) - A_{dr}(x_{r}^{n}) \right).$$
(6)

Let  $\varepsilon > 0$ . Then for *n* large and  $0 \leq s \leq u \leq 1$  with |u - s| small

$$\begin{aligned} x_{s,t}^{n} &= [x^{n}]_{\mathcal{C}_{[s,u]}^{1-\mathsf{var}}} \leqslant C(p,\eta) \left( [A]_{\mathcal{C}_{[s,u]}^{p-\mathsf{var}}(\mathcal{C}^{\eta})} + [A]_{\mathcal{C}_{[s,u]}^{p-\mathsf{var}}(\mathcal{C}^{\eta})} [x^{n}]_{\mathcal{C}_{[s,u]}^{1-\mathsf{var}}}^{\eta} + \varepsilon \right) \\ \implies [x^{n}]_{\mathcal{C}_{[s,u]}^{1-\mathsf{var}}} \leqslant C(p,\eta) \frac{[A]_{\mathcal{C}_{[s,u]}^{p-\mathsf{var}}(\mathcal{C}^{\eta})} + \varepsilon}{1 - C(p,\eta)[A]_{\mathcal{C}_{[s,u]}^{p-\mathsf{var}}(\mathcal{C}^{\eta})}}. \end{aligned}$$

## Theorem (A., Richard, and Tanré 2021)

For  $H < \sqrt{2} - 1$  and  $\phi$  a nonnegative finite measure, there exists a path-by-path solution to (•). Furthermore, building on this construction, we can also construct a weak solution.

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#### Corollary

As a corollary of the general Theorem one gets, for a nonnegative bump function  $\xi$  and  $\varepsilon > 0$ , a weak solution to

$$X_t = \int_0^t |X_r|^{-3/4+\varepsilon} \xi(X_r) dr + W_t.$$

## Motivation and definitions

## Existence of a solution via nonlinear Young integration



Definition (Pathwise uniqueness vs. path-by-path uniqueness)

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- We say that pathwise uniqueness holds if for any weak solutions X, Y defined on the same filtered probability space, X ≡ Y.
- We say that path-by-path uniqueness for (•) holds if for any probability space on which a Brownian motion W is defined, there exists a null-set N such that for ω ∉ N, there exists a unique solution to

$$X_t(\omega) = \int_0^t \phi(r, X_r(\omega)) dr + W_t(\omega).$$

path-by-path uniqueness

pathwise uniqueness

## Uniqueness and counterexamples

$$X_{t} = X_{0} + \int_{0}^{t} \phi(r, X_{r}) dr + W_{t}, \quad X_{0} = x_{0} \in \mathbb{R}^{d}$$
 (•)

Theorem (Krylov and Röckner 2005)

Let  $\phi \in L^q([0, T], L^p(\mathbb{R}^d))$  for  $p \ge 2, q > 2$  with d/p + 2/q < 1. Then there exists a pathwise unique strong solution to  $(\bullet)$ .

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#### Theorem (Davie 2007)

Let  $\phi : [0, T] \times \mathbb{R}^d \to \mathbb{R}^d$  be bounded and measurable. Then path-by-path uniqueness holds.

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## Counterexamples (Shaposhnikov and Wresch 2020, A. 2022)

One can construct drifts  $\phi : [0, T] \times \mathbb{R}^d \to \mathbb{R}^d$  such that

- there is existence of path-by-path solutions to (•), but there exists no weak solution;
- there exists a pathwise unique weak solution to (•), but path-by-path uniqueness is lost.

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## Uniqueness for unbounded functions

$$X_t = \int_0^t \phi(X_r) dr + W_t \iff \tilde{X}_t = \int_0^t \phi(\tilde{X}_r + W_r) dr \qquad (\bullet)$$

## Theorem (A., ongoing work)

Let  $\alpha > -1/2$  and let  $\phi(x) \coloneqq \mathbb{1}_{\{x \neq 0\}} |x|^{\alpha} \xi(x)$  for a bump function  $\xi$ . Then there exists a unique path-by-path solution to equation (•).

### Proof.

• Let 
$$\tilde{X}^1 \neq \tilde{X}^2$$
 be solutions to (•)

- W.I.o.g.  $\exists$  time interval [s, t] on which  $|\tilde{X}^1 + W| > |\tilde{X}^2 + W|$
- By monotonicity of  $\phi$ , on [s, t],  $\phi(\tilde{X}^1 + W) < \phi(\tilde{X}^2 + W)$  (if  $\tilde{X}^2 + W \neq 0$ )
- $\implies \tilde{X}^1 \tilde{X}^2$  is monotone on [s, t]. Finding a nonlinear Young integral equation that is solved by  $\tilde{X}^1 \tilde{X}^2$ , we get

$$[\tilde{X}^1 - \tilde{X}^2]_{\mathcal{C}^{1\text{-var}}_{[s,t]}} = |(\tilde{X}^1 - \tilde{X}^2)_{s,t}| \leq C(t-s)^{\gamma} [\tilde{X}^1 - \tilde{X}^2]_{\mathcal{C}^{1\text{-var}}_{[s,t]}}.$$

Solution to a nonlinear Young integral equation Solution to a nonlinear Young integral equation

- Ensure sufficient regularity of  $T^{\tilde{X}^2+W}\phi$  in order to write  $\tilde{X}^1 \tilde{X}^2$  as the solution to a nonlinear Young integral equation
- <sup>(2)</sup> Ruling out the possibility that  $\tilde{X}^2 + W = 0$  on a set of positive measure to ensure that  $\tilde{X}^1 \tilde{X}^2$  is actually nondecreasing on [s, t]

- Ensure sufficient regularity of  $T^{\tilde{X}^2+W}\phi$  in order to write  $\tilde{X}^1 \tilde{X}^2$  as the solution to a nonlinear Young integral equation
- **2** Ruling out the possibility that  $\tilde{X}^2 + W = 0$  on a set of positive measure to ensure that  $\tilde{X}^1 \tilde{X}^2$  is actually nondecreasing on [s, t]
- Open problem: How to ensure 2 in the fractional Brownian motion case?

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## Questions please!